

1. Consider a hollow cylinder of initial inner radius R_{in} and outer radius R_{out} , see Figure 1, and assume that the cylinder is in this configuration in a stress free state. Further, assume that the material of which is the cylinder made is a homogeneous isotropic *incompressible* elastic material specified by constitutive relation

$$\mathbb{T} = -p\mathbb{1} + \mu(\mathbb{B} - \mathbb{1}),$$

where μ is a positive constant and \mathbb{B} denotes the left Cauchy–Green tensor with respect to the initial configuration with the inner radius R_{in} and the outer radius R_{out} .

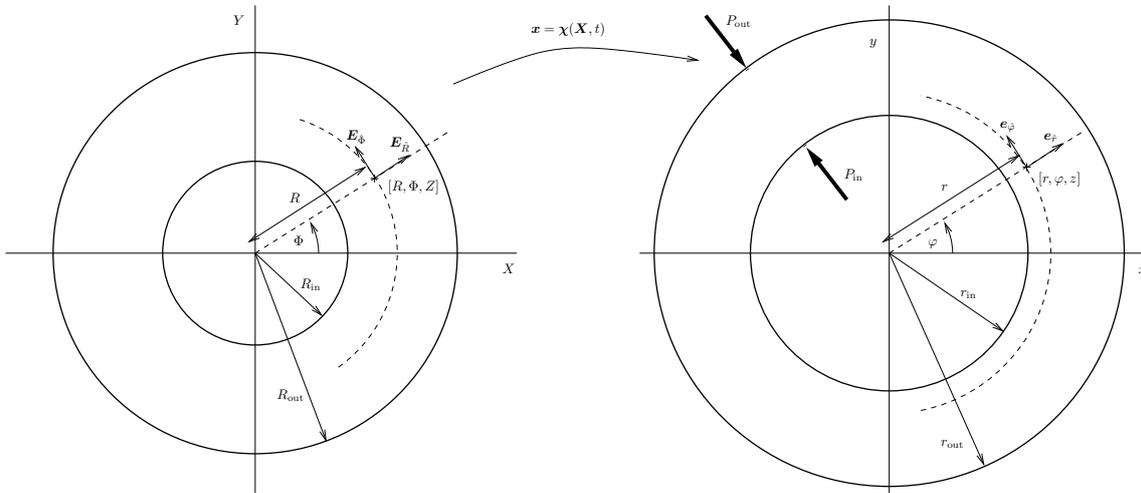


Figure 1: Inflation of a hollow cylinder made of an incompressible elastic material.

Let us now apply a pressure P_{in} inside the cylinder and a pressure P_{out} outside the cylinder. If the inner pressure is higher than the outer pressure, then the cylinder inflates. The task is to find a relation between the relative change in the void area

$$c =_{\text{def}} \frac{r_{\text{in}}^2 - R_{\text{in}}^2}{R_{\text{in}}^2}$$

and the pressure difference $P_{\text{in}} - P_{\text{out}}$.

Find the answer using *linearised elasticity* theory, that is use the governing equations in the form

$$\begin{aligned} \text{div } \mathbb{T} &= \mathbf{0}, \\ \text{Tr}(\nabla \mathbf{U}) &= 0, \end{aligned}$$

where $\mathbb{T} =_{\text{def}} -p\mathbb{1} + 2\mu\mathbb{E}$ and $\mathbb{E} =_{\text{def}} \frac{1}{2}(\nabla \mathbf{U} + (\nabla \mathbf{U})^\top)$. The boundary conditions read

$$\begin{aligned} \mathbb{T} \mathbf{E}_{\hat{z}}|_{R=R_{\text{in}}} &= P_{\text{in}} \mathbf{E}_{\hat{z}}|_{R=R_{\text{in}}}, \\ \mathbb{T} \mathbf{E}_{\hat{z}}|_{R=R_{\text{out}}} &= P_{\text{out}} \mathbf{E}_{\hat{z}}|_{R=R_{\text{out}}}, \end{aligned}$$

while the deformation is assumed to take the form

$$\begin{aligned} r &= f(R), \\ \varphi &= \Phi, \\ z &= Z. \end{aligned}$$

The result should be identical to the result

$$P_{\text{out}} - P_{\text{in}} \approx \mu \int_{r=R_{\text{in}}}^{R_{\text{out}}} \frac{2cR_{\text{in}}^2}{r^3} dr$$

that we have already obtained via linearisation of the solution to the complete system of nonlinear governing equations.

The formula for the divergence of a tensorial quantity \mathbb{A} in the cylindrical coordinate system reads

$$\operatorname{div} \mathbb{A} = \begin{bmatrix} \frac{\partial A^{\hat{r}}_{\hat{r}}}{\partial r} + \frac{1}{r} \left(\frac{\partial A^{\hat{r}}_{\hat{\varphi}}}{\partial \varphi} - A^{\hat{\varphi}}_{\hat{\varphi}} + A^{\hat{r}}_{\hat{r}} \right) + \frac{\partial A^{\hat{r}}_{\hat{z}}}{\partial z} \\ \frac{\partial A^{\hat{\varphi}}_{\hat{r}}}{\partial r} + \frac{1}{r} \left(\frac{\partial A^{\hat{\varphi}}_{\hat{\varphi}}}{\partial \varphi} + A^{\hat{r}}_{\hat{\varphi}} + A^{\hat{\varphi}}_{\hat{r}} \right) + \frac{\partial A^{\hat{\varphi}}_{\hat{z}}}{\partial z} \\ \frac{\partial A^{\hat{z}}_{\hat{r}}}{\partial r} + \frac{1}{r} \left(\frac{\partial A^{\hat{z}}_{\hat{\varphi}}}{\partial \varphi} + A^{\hat{z}}_{\hat{r}} \right) + \frac{\partial A^{\hat{z}}_{\hat{z}}}{\partial z} \end{bmatrix}.$$