

# Věta 14.1 [Tot. dif a monitör, derivace.]

necht'  $\exists df(a)$ . Potom:

1.  $f$  je monitör v bodě  $a$

2. pro  $\forall v$  je  $\frac{\partial f}{\partial v}(a) = df(a)v$ .

Dŕ. máme:  $f(a+h) = f(a) + Lh + R(h)$ ,

kde  $L = df(a)$  je lineární, a tedy

$$\|Lh\| \leq C\|h\| \rightarrow 0, \quad h \rightarrow 0$$

a dále  $R(h) = o(\|h\|)$ ,  $h \rightarrow 0$ ,

$$\Rightarrow R(h) = \underbrace{\frac{R(h)}{\|h\|}}_{\rightarrow 0} \cdot \underbrace{\|h\|}_{\rightarrow 0} \rightarrow 0, \quad h \rightarrow 0$$

CELKEM:  $f(a+h) = f(a) + \underbrace{Lh + R(h)}_{\rightarrow 0}$

neloží  $f(x) \rightarrow f(a)$ ,  $x \rightarrow a$   $\rightarrow f(a), h \rightarrow 0$

$\Leftrightarrow$  monitör v bodě  $a$   
 („Věta 2.5“)

$$\underline{2.} \quad f(a+tv) = f(a) + \underbrace{L(tv)}_{tL(v) \text{ (lineární } L)} + R(tv)$$

$$\Rightarrow \frac{1}{t} [f(a+tv) - f(a)] = \underbrace{L(v)}_{\rightarrow L(v)} + \frac{R(tv)}{t}$$

nechť:  $\frac{R(tv)}{t} = \underbrace{\frac{R(tv)}{\|tv\|}}_{\rightarrow 0} \cdot \underbrace{\frac{\|tv\|}{t}}_{\frac{|t|\|v\|}{t} = (\text{sgn } t)\|v\| \dots \text{omezené}} \rightarrow 0, t \rightarrow 0$

Věta 14.2. [Derivace a spojitost, 1. dif.]

1. Nechť  $\frac{\partial f}{\partial x_i}$  jsou omezené na  $U(a)$ , pro  $t_i$

Platí  $f$  je spojitě v  $U(a)$ .

2. Nechť  $\frac{\partial f}{\partial x_i}$  jsou spojitě v  $U(a)$ , pro  $t_i$ .

Platí  $\exists df(a)$ .

Důk. BUŇNO  $a=0$ ; nechť  $h \in U(0)$  d'no.

promocné body:  $\underline{h}^0 = (0, 0, \dots, 0) = \underline{0}$

$$\underline{h}^1 = (h_1, 0, \dots, 0)$$

$$\underline{h}^2 = (h_1, h_2, 0, \dots)$$

$$\underline{h}^N = (h_1, h_2, \dots, h_N)$$

$$\begin{aligned} f(\underline{h}) - f(\underline{0}) &= f(\underline{h}^N) - f(\underline{h}^{N-1}) \\ &+ f(\underline{h}^{N-1}) - f(\underline{h}^{N-2}) \\ &\vdots \\ &+ f(\underline{h}^1) - f(\underline{h}^0) \\ &= \sum_{i=1}^N \underbrace{f(\underline{h}^i) - f(\underline{h}^{i-1})}_{P_i} \end{aligned}$$

blízké posuvné: označme

$$\varphi^i(t) = f(t h_i \underline{e}^i + \underline{h}^{i-1}), \quad i=1, \dots, N$$

$$P_i = \varphi^i(1) - \varphi^i(0) = (\varphi^i)'(\tau_i), \quad \tau_i \in (0, 1)$$

↑ Lagrange!!

$$= \frac{\partial f}{\partial x_i}(\underline{\theta}^i) h_i, \quad \text{kte } \underline{\theta}^i = \tau_i h_i \underline{e}^i + \underline{h}^{i-1}$$

CELKEDŐ:  $|f(\underline{h}) - f(\underline{0})| \leq \sum_{i=1}^N |P_i|$

$$\leq \sum_{i=1}^N \underbrace{\left| \frac{\partial f}{\partial x_i}(\underline{\theta}^i) \right|}_{\leq C} \underbrace{|h_i|}_{\leq \|h\|} \leq NC \cdot \|h\|$$

$$\leq C \|h\|$$

Ady:  $f(\underline{h}) \rightarrow f(\underline{0}), \underline{h} \rightarrow 0.$   $\pm \frac{\partial f}{\partial x_i}(\underline{0})$

ad 2.  $f(\underline{h}) - f(\underline{0}) = \sum_{i=1}^N \frac{\partial f}{\partial x_i}(\underline{\theta}^i) h_i$

$$= \underbrace{\sum_{i=1}^N \frac{\partial f}{\partial x_i}(\underline{0}) h_i}_{\nabla f(\underline{0}) h} + \underbrace{\sum_{i=1}^N \left( \frac{\partial f}{\partial x_i}(\underline{\theta}^i) - \frac{\partial f}{\partial x_i}(\underline{0}) \right) h_i}_{r(h)}$$

... összekérem  
 van tot. dif. ...

... nyilvánvalóan:  
 $\frac{r(h)}{\|h\|} \rightarrow 0, h \rightarrow 0$

rezimé:  $\underline{h} \rightarrow 0 \Rightarrow \underline{\theta}^i \rightarrow 0$

$$\text{a tedy } \frac{|R(h)|}{\|h\|} \leq \sum_{j=1}^N \underbrace{\left| \frac{\partial f}{\partial x_i}(\theta^i) - \frac{\partial f}{\partial x_i}(0) \right|}_{\rightarrow 0} \underbrace{\frac{|h_i|}{\|h\|}}_{\leq 1}$$

... možná

$$\frac{\partial f}{\partial x_i} \text{ v bodě } a=0 \dots$$

Věta 14.3 [Tot. dif součtu a složení.]

1. Necht'  $\exists df(a), dg(a)$ . Potom  $\exists d(f+g)(a)$   
a rovně  $df(a) + dg(a)$ .

2. Necht'  $\exists df(a)$ , necht'  $\exists dg(b)$ , kde  
 $b = f(a)$ . Potom  $\exists d(g \circ f)(a)$  a rovně  
 $dg(f(a))df(a)$ .

Důk. 1. máme, že platí

$$f(a+h) = f(a) + Lh + R(h)$$

$$g(a+h) = g(a) + Kh + w(h),$$

$$\text{kde } L = df(a), K = dg(a)$$

$$R(h), w(h) = o(\|h\|), h \rightarrow 0$$

$$\begin{aligned} \Rightarrow (f+g)(a+h) &= f(a+h) + g(a+h) \\ &= \underbrace{f(a) + g(a)}_{(f+g)(a)} + \underbrace{Lh + Kh}_{(L+K)h} + \underbrace{r(h) + w(h)}_{\begin{matrix} \text{"} \\ o(\|h\|), \\ h \rightarrow 0 \end{matrix}} \end{aligned}$$

a tedy:  $L+K = d(f+g)(a)$

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2. dle předpokladů:

$$f(a+h) = f(a) + Lh + r(h)$$

$$g(b+k) = g(b) + Kk + w(k)$$

kde  $L = df(a)$ ,  $K = dg(b)$ ,  $b = f(a)$

$$r(h) = o(\|h\|), \quad w(k) = o(\|k\|)$$

$h \rightarrow 0 \qquad k \rightarrow 0$

$$\Rightarrow (g \circ f)(a+h) = g(f(a+h))$$

$$= g(\underbrace{f(a)}_b + \underbrace{Lh + r(h)}_k)$$

$$= g(b) + K(Lh + r(h)) + w(Lh + r(h))$$

$$= (g \circ f)(a) + KLh + \gamma^1(h) + \gamma^2(h)$$

$$\text{bdel } KL = dg(\sigma)df(a)$$

$$\gamma^1(h) = KR(h)$$

$$\gamma^2(h) = w(Lh + R(h))$$

... seer ukse'rat:

$$\gamma^{1,2}(h) = o(\|h\|), h \rightarrow 0$$

$$\frac{\gamma^1(h)}{\|h\|} = \frac{KR(h)}{\|h\|} = K \left( \frac{R(h)}{\|h\|} \right) \rightarrow K0 = 0$$

... moji'or K  
(line'ar)

$$\frac{\gamma^2(h)}{\|h\|} = \begin{cases} 0, & Lh + R(h) = 0 \\ \frac{w(Lh + R(h))}{\|Lh + R(h)\|} \cdot \frac{\|Lh + R(h)\|}{\|h\|} \end{cases}$$

$\rightarrow 0$

die "VOLF"

omezene,  
nelos'...

$$\frac{\|Lh + r(h)\|}{\|h\|} \leq \underbrace{\frac{\|Lh\|}{\|h\|}}_{\leq C} + \underbrace{\frac{\|r(h)\|}{\|h\|}}_{\rightarrow 0}$$

neboť:  $\|Lh\| \leq C\|h\|$

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Pozor. tot. dif. součinu?

mechs:  $f(x), g(x): \mathcal{U}(a) \rightarrow \mathbb{R}$

TRIK:  $f(x) \cdot g(x) = (\Phi \circ F)(x)$

kde  $\Phi: (u, v) \mapsto uv$

$F: x \mapsto (f(x), g(x))$

nejmé  $\Phi \in C^1$ ,  $\nabla \Phi = \left( \frac{\partial \Phi}{\partial u}, \frac{\partial \Phi}{\partial v} \right) = (v, u)$

... Věta 14.2  $\Rightarrow d\Phi|_{(u,v)}: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$(x_1, x_2) \mapsto vx_1 + ux_2$$

... dále:  $dF(a) = (df(a), dg(a))$

... V. 14.3  $\Rightarrow d(f \cdot g)(a) = d(\Phi \circ F)(a)$

$$= d\Phi(F(a)) dF(a) = g(a)df(a) + f(a)dg(a)$$



Posu... zímj konec dikaru  $\sqrt{\epsilon}$  14.3, 2.

$$\text{cil: } \omega^2(h) = \omega(Lh + R(h)) = o(\|h\|)$$

$$\text{g: } \forall \epsilon > 0 \exists \delta > 0 \text{ a. r. } 0 < \|h\| < \delta$$

$$\Rightarrow \frac{\|\omega(Lh + R(h))\|}{\|h\|} < \epsilon$$

$$\text{neboli } \|\omega(Lh + R(h))\| < \epsilon \|h\|$$

... pomocne' rovnice:

$$\|Lh + R(h)\| \leq \|Lh\| + \|R(h)\|$$

$$\leq C \|h\| + \frac{\|R(h)\|}{\|h\|} \cdot \|h\|$$

$< 1$ , je-li  
 $h$  blizko 0

$$\Rightarrow \exists \delta_1 > 0 \text{ a. r. } 0 < \|h\| < \delta_1$$

$$\Rightarrow \|Lh + R(h)\| < (C+1) \|h\|$$

$$\text{dale: } \omega(\mathfrak{z}) = o(\mathfrak{z}), \mathfrak{z} \rightarrow 0$$

$$\text{a tedy: } \exists \Delta > 0 \text{ a. r. } 0 < \|\mathfrak{z}\| < \Delta$$

$$\Rightarrow \|\omega(\mathfrak{z})\| < \frac{\epsilon}{C+1} \|\mathfrak{z}\|$$

... dělá, položí  $\delta_2 = \frac{\Delta}{C+1}$

a konečně  $\delta = \min \{ \delta_1, \delta_2 \}$ .

Nechť nyní  $0 < \|h\| < \delta \dots$  chceme položit  $g_2 = Lh + R(h)$ , ale je třeba rozlišit dvě případy:

(i)  $Lh + R(h) = 0 \dots$  pak aleřejmě

$$\|w(Lh + R(h))\| = 0 < \varepsilon \|h\|,$$

(neboť  $w(0) = 0$ )

(ii)  $Lh + R(h) = g_2 \neq 0$ , pak máme

$$0 < \|Lh + R(h)\| < (C+1)\|h\| < \Delta$$

$$< \delta_2 = \frac{\Delta}{C+1}$$

a tedy máme:

$$\begin{aligned} \|w(Lh + R(h))\| &< \frac{\varepsilon}{C+1} \|Lh + R(h)\| \\ &< (C+1)\|h\| \\ &< \varepsilon \|h\| \end{aligned}$$