

# Numerical Solution of ODEs

Exercise Class

21st November 2024

## Dynamical Systems

Consider Van der Pol's oscillator:

$$x_1' = f_1(x) = x_2 \quad (1)$$

$$x_2' = f_2(x) = -x_1 + 2ax_2 - x_1^2x_2 \quad (2)$$

with initial conditions  $x_0 \in \mathbb{R}^2$  at time  $t_0 = 0$ . In order to solve this we require a *stiff* solver such as `ode23s` or `ode45s`.

## Steady State

This problem has a steady state at  $\mathbf{x}^* = (0, 0)^\top \in \mathbb{R}^2$ , but is it A-stable? In order to determine this we need to compute the eigenvalues of the Jacobian matrix

$$A = \begin{pmatrix} \frac{\partial f_1}{\partial x_2}(\mathbf{x}^*) & \frac{\partial f_1}{\partial x_1}(\mathbf{x}^*) \\ \frac{\partial f_2}{\partial x_1}(\mathbf{x}^*) & \frac{\partial f_2}{\partial x_2}(\mathbf{x}^*) \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 - 2x_1^*x_2^* & 2a - (x_1^*)^2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 2a \end{pmatrix}.$$

From the characteristic polynomial we can compute that the spectrum of  $A$  is

$$\sigma(A) = \left\{ a + \sqrt{a^2 + 1}, a - \sqrt{a^2 + 1} \right\}.$$

The steady state is A-stable if  $\max_{\lambda \in \sigma(A)} \operatorname{Re}(\lambda) < 0$ . So we evaluate for different values of  $a$ :

$|a| < 1$ : Here  $\sigma(A) = \{a + bi, a - bi\}$ , for some  $b \in \mathbb{R}$ ; therefore,  $\max_{\lambda \in \sigma(A)} \operatorname{Re}(\lambda) = a$ . Hence, we have that  $\mathbf{x}^*$  is A-stable if  $a < 0$  and  $\mathbf{x}^*$  is unstable if  $a > 0$ .

$|a| > 1$ : Here  $\sigma(A) = \{a + b, a - b\}$ , for some  $b \in [0, |a|]$ ; therefore,  $\max_{\lambda \in \sigma(A)} \operatorname{Re}(\lambda) = a + b$ . Hence, we have that  $\mathbf{x}^*$  is A-stable if  $a < 0$  and  $\mathbf{x}^*$  is unstable if  $a > 0$ .

## Linearisation

We can generate the linearised version of Van der Pol's oscillator using Taylor's expansion around  $\mathbf{x}^*$ :

$$\mathbf{x}' = f(\mathbf{x}) = f(\mathbf{x}^*) + A(\mathbf{x} - \mathbf{x}^*) + \underbrace{g(\mathbf{x} - \mathbf{x}^*)}_{\substack{\text{Higher-order terms} \\ \text{discarded}}}.$$

This gives the linearised form as

$$\begin{aligned} x_1' &= x_2, \\ x_2' &= -x_1 + 2ax_2. \end{aligned}$$

## Exercises

1. Consider Van der Pol's oscillator given by (1)–(2).
  - (a) Plot the result of solving forwards to  $T_f$  and backwards to  $T_b$  for the following situations using `ode23s`:
    - i.  $x_0 = (1, 1)^\top$ ,  $a = -0.1$ ,  $T_f = 20$ ,  $T_b = -1.8$
    - ii.  $x_0 = (0, 0)^\top$ ,  $a = -0.1$ ,  $T_f = 20$ ,  $T_b = -1.5$
    - iii.  $x_0 = (1, 1)^\top$ ,  $a = 1.1$ ,  $T_f = 20$ ,  $T_b = -1.5$
    - iv.  $x_0 = (-1, 6)^\top$ ,  $a = 1.1$ ,  $T_f = 20$ ,  $T_b = -0.4$
  - (b) For Van der Pol's oscillator study the steady state numerically (see `vdpol_steady`) for  $a = -1.1, 0.5, 1.1$ .
  - (c) Solve Van der Pol's oscillator with  $a = -0.1$  with initial condition  $x_0 = (1, 1)^\top$  in the time interval  $[0, 120]$  using the following numerical methods and time step size  $\tau$ :
    - i. Euler (`eul.m`) with  $\tau = 0.4$
    - ii. Euler (`eul.m`) with  $\tau = 0.05$
    - iii. Implicit Euler (`ieuler.m`) with  $\tau = 0.4$
2. Consider the initial value problem

$$\begin{aligned}x'_1 &= (a - b)x_1 - cx_2 + x_1(x_3 + d(1 - x_3^2)) \\x'_2 &= cx_1 + (a - b)x_2 + x_2(x_3 + d(1 - x_3^2)) \\x'_3 &= ax_3 - (x_1^2 + x_2^2 + x_3^2)\end{aligned}$$

with initial conditions  $x_0 \in \mathbb{R}^3$  at time  $t_0 = 0$ . This problem has two steady states,

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{and} \quad x^* = \begin{pmatrix} 0 \\ 0 \\ a \end{pmatrix}.$$

- (a) Compute the Jacobian  $A \in \mathbb{R}^{3 \times 3}$  at  $x^*$  and check if this steady state is A-stable for:
  - i.  $a = 1.0, b = 3, c = 0.25, d = 0.2$
  - ii.  $a = 1.95, b = 3, c = 0.25, d = 0.2$
  - iii.  $a = 2.02, b = 3, c = 0.25, d = 0.2$

*Remark 1.* Attempt to deduce the eigenvalues analytically if possible, and then verify by numerically calculating the eigenvalues using the MATLAB `eig` function.
- (b) Plot and estimate the  $\omega$ -limit for the same parameters  
*Hint.* Solve upto time  $T = 2000$ .