

## **Regression in Sobolev Spaces Using Total Least Squares**

*Michal Peˇsta* ♯



## CHARLES UNIVERSITY IN PRAGUE

 $\bullet$  input data  $[x_i,y_i],\, i=1,\ldots,n$ • observations  $[x, y] \equiv$  $\sqrt{ }$  $(x_1, ..., x_n)^\top, (y_1, ..., y_n)^\top$ are considered to be measured with additive errors  $[\delta, \varepsilon]$ 

Faculty of Mathematics and Physics, Department of Probability and Mathematical Statistics

 $\boldsymbol{\omega}$ 

 $\boldsymbol{\varpi}$ 

Statist

8

 $\overline{\textbf{C}}$ 

 $\mathbf O$ 

Backgl

ematica

Math

 $\boldsymbol{\omega}$ 

• unobservable true values  $[x+\delta, y+\varepsilon]$  satisfy an unknown functional relationship

 $\bullet$  unknown function  $f$  is thought to be smooth • searching for a suitable estimator  $\hat{f}$  ... misfit needs to be as small as possible

**Mathematical Background & Statistical Setup** • we want a modelling technique to be applicable on various types (large number) of data  $\Longrightarrow$  nonparametric approach

 $\bullet$  smoothness of unknown function  $f$  needs to be ensured ... but kernels, splines or wavelets can be too restrictive

## $y_i + \varepsilon_i = f(x_i + \delta_i), \quad i = 1, \dots, n$

## Regression

- Euclidean norm of errors  $\leftarrow$  orthogonal regression  $\equiv$  Total Least Squares (TLS) approach
- statistical assumptions for so-called Errors-in-Variables (EIV) model:
- **–** rows of the errors  $[\delta, \varepsilon]$  are iid with common zero mean and covariance matrix  $\sigma^2 \mathbf{I}_2$  where  $\sigma^2 > 0$  is unknown
- **–** no special distributional assumptions (i.e. no normality of errors)



$$
\left(\mathcal{H}^m, \| \cdot \|_{Sob,m} \right) := \left\{ g \in \mathsf{L}^2 \, : \, \| g \|_{Sob,m} := \left( \sum_{i=0}^m \int |g^{(i)}(t)|^2 \mathrm{d} t \right)^{1/2} < + \infty \right\}
$$

**Estimator, Properties and Examples SD** Example and  $\boldsymbol{\omega}$ tie  $\mathbf 0$ 0

• using Riesz representation theorem, Arzelà-Ascoli theorem and solving ODE one may easily derive so-called representor matrix  $\Psi \equiv \Psi({\bf x} + {\bm \delta}) \ldots$  see [2]

• the better the fit, the wilder the function and vice versa, i.e.

$$
\frac{\text{small}}{\text{large}} \left\| \begin{bmatrix} \delta \\ \epsilon \end{bmatrix} \right\|_2 \right\|_2 \right\} \frac{\text{large}}{\text{small}} \|f\|_{Sob,m}
$$

 $\Rightarrow$  find a reasonable compromise between misfit (Euclidean norm of the error vector) and smoothness (Sobolev norm of the estimator function) ... choice of a smoothing parameter  $\chi > 0$ 

$$
f \in \mathcal{H}^m, \delta \in \mathbb{R}^n, \varepsilon \in \mathbb{R}^n \left\{ \left\| \begin{bmatrix} \delta \\ \varepsilon \end{bmatrix} \right\|_2^2 + \chi \|f\|_{Sob,m}^2 \right\}, \quad \text{s.t. } \mathbf{y} + \varepsilon = \mathbf{f}(\mathbf{x} + \delta)
$$

 $f \!\in\! \mathcal{H}^m, \!\boldsymbol{\delta} \!\!\in\! \mathbb{R}^n, \! \boldsymbol{\varepsilon} \!\in\! \mathbb{R}^n$ Sob,m

[1] Paige, C. C. and Strakoš, Z.: Core problems in linear algebraic systems, *SIAM J. on Matrix Analysis and Applications*, *27*, 861–875, 2006. [2 ] Yatchew, A. J. and Bos, L.: Nonparametric least squares estimation and testing of economic models, *J. of Quan. Economics*, *13*, 81–131, 1997.

Acknowledgments: The present work was supported by the Grant Agency of the Czech Republic (grant 201/05/H007).  $\sharp$  pesta@karlin.mff.cuni.cz, 2008

$$
\begin{aligned}\n\int_{f \in \mathcal{H}^m, \delta \in \mathbb{R}^n, \varepsilon \in \mathbb{R}^n} \left\{ \left\| \begin{bmatrix} \delta \\ \varepsilon \end{bmatrix} \right\|_2^2 + \chi \|f\|_{Sob,m}^2 \right\}, & \text{s.t. } \mathbf{y} + \varepsilon = \mathbf{f}(\mathbf{x} + \delta) \\
\downarrow & \qquad \qquad \downarrow & \qquad \downarrow &
$$

 $\Rightarrow$  fit a function from a general class of smooth functions  $\rightsquigarrow$  Sobolev spaces



atively easy to compute, but complicated formulas • consistency (assumption: variables "spread out" fast enough) P  $|\hat{f}(t) - f(t)|$ sup  $\stackrel{\text{I}}{\rightarrow} 0, \quad n \rightarrow \infty$ t • moreover, if the distribution of the rows of  $[\delta, \varepsilon]$  possesses finite fourth moment  $\rightsquigarrow$  asymptotic normality **Easter Island and Darwin, Australia** Atmospheric pressure differences differ  $\frac{1}{5}$ 0 5 10 15  $\overline{10}$  $\bar{\Omega}$ S Atmosph  $\circ$ 0 50 100 150 Months El Niño – Southern Oscillation **National Institute of Standards and Technology, USA**



• this method works without a prior knowledge of functional relation or error distribution; extendable into multivariate case

• References: