

Lecture 2 | 03.03.2025

# Multivariate regression model (likelihood estimation & statistical properties)

# Standard notation

- longitudinal observations  $\mathcal{D}_L \equiv \{(Y_{ij}, \mathbf{X}_{ij}^\top)^\top; i = 1, \dots, N; j = 1, \dots, n_i\}$ 
  - for  $N \in \mathbb{N}$  independent subjects observed repeatedly  $n_i \in \mathbb{N}$  times
  - dependent variable  $Y_{ij} \in \mathbb{R}$  and covariates  $\mathbf{X}_{ij} \in \mathbb{R}^p$ , for some  $p \in \mathbb{N}$
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↔ what does it mean to have a **balanced data** set in hand?

# The main aims of longitudinal analysis

- ❑ Estimation of the **cross-sectional dependence** structure (between subjects)  
(averaging across different subpopulations defined by specific value of the covariates)
- ❑ Estimation of the **time/spatial dependence** structure (within subjects)  
(time/spatial change within a specific subject while the subject's covariates change too)
  
- ❑ Inference on **marginal** vs. **hierarchical** means
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↔ the estimation and the following inference can be performed in terms of various characteristics and different inference tools

↔ the main interest will be given to the conditional distribution characterized by the conditional expectation in particular



# Common approaches to longitudinal data

## □ Naive methods

The longitudinal structure within a subject is firstly summarized into one (or more) characteristics and independent characteristics are regressed over independent subjects (e.g., separate time points analysis, area under the curve, analysis of endpoints, increments, covariance)

## □ Simple methods

Marginal models similar to a standard cross-sectional study, however, with an additional assumption on the variance – generally  $E\mathbf{Y}_i = \mathbf{X}_i^T \boldsymbol{\beta}$  and  $\text{Var} \mathbf{Y}_i = \mathbb{V}_i(\boldsymbol{\alpha})$ , where  $\boldsymbol{\alpha} \in \mathbb{R}^q$  and  $\boldsymbol{\beta} \in \mathbb{R}^p$  must be estimated

## □ Random effects models

Allow for marginal as well as hierarchical interpretation – the regression coefficients may vary across subjects (modifications due to random effects) and the models a priori assume a specific correlation structure among repeated observations within the subjects

## □ Transition models

Modelling the conditional expectation of  $Y_{ij}$  given past observations within the same subject and the explanatory variables  $X_{ij}$

## More general: multivariate regression

- **multivariate linear regression** as an extension of ordinary linear regression (*multivariate linear regression vs. multiple (multi-variable) regression*)
- general model formulation for  $\mathbb{Y} \in \mathbb{R}^{N \times n}$  and  $\mathbb{X} \in \mathbb{R}^{N \times p}$  ( $N \in \mathbb{N}$  and  $n \in \mathbb{N}$  repeated measurements within each subject)

$$\mathbb{Y} = \mathbb{X}\mathbb{B} + \mathbb{U} \quad | \quad Y_{ij} = \mathbf{X}_i^\top \beta_j + \varepsilon_{ij}$$

where  $\mathbb{Y} = (Y_{ij})_{i,j=1}^{N,n}$ ,  $\mathbb{X} = (X_{ij})_{i,j=1}^{N,p}$ ,  $\mathbb{B} = (\beta_{ij})_{i,j=1}^{p,n}$ , and  $\mathbb{U} = (\varepsilon_{ij})_{i,j=1}^{N,n}$

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- What are the corresponding data (let's denote the data as  $\mathcal{D}_S$ )? (*recall, that the vector of the explanatory covariates is subject specific*)
- What is the meaning of the formulae above? (*note, that the time dependence is only reflected within  $\beta_j \in \mathbb{R}^p$* )
- What are the objects appearing in the expression?
- What are typical assumptions for such linear model?

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**Question:** What are the advantages or disadvantages of the longitudinal model formulation and the multivariate model formulation?

# Parameter estimation

## The main goal:

Estimation of the unknown parameters in  $\mathbb{B} \in \mathbb{R}^{p \times n}$  and the variance-covariance matrix of the random (row) vectors in  $\mathbb{U}$  (error terms)

## In general:

Under **different assumptions**  $\Rightarrow$  **different estimation** approaches  
 $\Rightarrow$  **different statistical properties** of the estimates

- ❑ least squares
- ❑ maximum likelihood
- ❑ generalized method of moments
- ❑ likelihood-based estimation
- ❑ ...

$\hookrightarrow$  specific set of the postulated assumptions implies certain statistical properties

(in most applications it is assumed that  $\mathbb{U}$  has uncorrelated, normally distributed rows with a zero mean vector and some specific variance-covariance matrix  $\Sigma$ )

# Multivariate normal distribution

- Multivariate normal model:**  $\mathbf{u}_i \sim N_n(\mathbf{0}, \Sigma)$  where  $\mathbb{U} = (\mathbf{u}_1, \dots, \mathbf{u}_N)^\top$   
 $\hookrightarrow$  where subject specific error vectors in  $\mathbb{U}$  are  $\mathbf{u}_i = (\varepsilon_{i1}, \dots, \varepsilon_{in})^\top$
- starting with the **multivariate normal regression model** the unknown parameters can be estimated by the method of the maximum likelihood
- general form of the density of the multivariate normal distribution

$$f(\mathbf{x}) = (2\pi)^{-n/2} |\Sigma|^{-1/2} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^\top \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}, \quad \mathbf{x} \in \mathbb{R}^n$$

- random sample  $\mathcal{D}_S = \{(\mathbf{Y}_i^\top, \mathbf{X}_i^\top)^\top; i = 1, \dots, N\}$ ,  $\mathbf{Y}_i \in \mathbb{R}^n$  and  $\mathbf{X}_i \in \mathbb{R}^p$
- the joint distribution of the random vectors  $(\mathbf{Y}_i^\top, \mathbf{X}_i^\top)^\top$  can be expressed/factorized as

$$F_{(\mathbf{Y}, \mathbf{X})}(\mathbf{y}, \mathbf{x}) = F_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x}) \cdot F_{\mathbf{X}}(\mathbf{x}) \quad \forall \mathbf{y} \in \mathbb{R}^n \quad \forall \mathbf{x} \in \mathbb{R}^p$$

# Likelihood and log-likelihood functions

- **likelihood function** for the data in  $\mathcal{D}_S$  and unknown means  $\mu_{ij} = \mathbf{X}_i^\top \beta_j$   
 $\hookrightarrow$  thus, the mean vector in the conditional distribution  $F_{\mathbf{Y}|\mathbf{X}}$  is  $\boldsymbol{\mu} = \mathbf{X}_i^\top \mathbb{B}$

$$L(\mathbb{B}, \Sigma, \mathcal{D}_S) = \left[ |2\pi\Sigma|^{-N/2} \cdot \exp \left\{ -\frac{1}{2} \sum_{i=1}^N (\mathbf{Y}_i - \mathbf{X}_i^\top \mathbb{B})^\top \Sigma^{-1} (\mathbf{Y}_i - \mathbf{X}_i^\top \mathbb{B}) \right\} \right]$$

- hence, the **log-likelihood function** can be expressed as

$$l(\mathbb{B}, \Sigma, \mathcal{D}_S) = -\frac{N}{2} \log |2\pi\Sigma| - \frac{1}{2} \text{trace} \left[ (\mathbf{Y} - \mathbf{X}\mathbb{B})\Sigma^{-1}(\mathbf{Y} - \mathbf{X}\mathbb{B})^\top \right]$$

# The empirical estimation of $\mathbb{B}$

↔ under the assumption that the matrix  $\mathbf{X}^\top \mathbf{X}$  has a full rank ( $p \in \mathbb{N}$ ), the maximum likelihood estimates of the mean parameters in  $\mathbb{B} \in \mathbb{R}^{p \times n}$  are given by the expression

$$\hat{\mathbb{B}}_N = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{Y}$$

- denote the **fitted values** as  $\hat{\mathbf{Y}} = \mathbf{X} \hat{\mathbb{B}}_N$
- denote the **residuals** as  $\hat{\mathbf{U}} = \mathbf{Y} - \hat{\mathbf{Y}} = \mathbf{Y} - \mathbf{X} \hat{\mathbb{B}}_N$
- denote the corresponding (regression) projection matrix as  $\mathbb{H} = \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$  and the residual projection matrix as  $\mathbb{P} = (\mathbf{I} - \mathbb{H})$



## Estimation of variance-covariance matrix

↔ under the assumption that the matrix  $\mathbb{X}^\top \mathbb{X}$  has a full rank ( $p \in \mathbb{N}$ ), the **maximum likelihood estimate** of the variance-covariance matrix  $\Sigma \in \mathbb{R}^{n \times n}$  is given by the expression

$$\hat{\Sigma}_N = \frac{1}{N} \mathbb{Y}^\top (\mathbb{I} - \mathbb{H}) \mathbb{Y} = \frac{1}{N} \hat{\mathbb{U}}^\top \hat{\mathbb{U}},$$

↔ the projection matrix  $\mathbb{H}$  is also called the **hat matrix** and it projects from the  $N$ -dimensional real space  $\mathbb{R}^N$  into a  $p$ -dimensional linear subspace. Alternatively, the matrix  $(\mathbb{I} - \mathbb{H})$  is the projection matrix of the orthogonal projection into the residual subspace (the  $(N - p)$ -dimensional subspace of  $\mathbb{R}^N$ )

# Useful formulae for derivations

- Linear form for  $\mathbf{a} \in \mathbb{R}^p$  and  $\mathbf{x} \in \mathbb{R}^p$

$$\frac{\partial \mathbf{a}^\top \mathbf{x}}{\partial \mathbf{x}} = \frac{\partial \mathbf{x}^\top \mathbf{a}}{\partial \mathbf{x}} = \mathbf{a}$$

- Quadratic form for  $\mathbb{A} \in \mathbb{R}^{p \times p}$  (symmetric matrix)

$$\frac{\partial \mathbf{x}^\top \mathbb{A} \mathbf{x}}{\partial \mathbf{x}} = 2\mathbb{A}\mathbf{x} \quad \text{and} \quad \frac{\partial^2 \mathbf{x}^\top \mathbb{A} \mathbf{x}}{\partial \mathbf{x} \partial \mathbf{x}^\top} = 2\mathbb{A}$$

- Trace of a matrix  $\mathbb{X}$

$$\frac{\partial \text{trace} \mathbb{X} \mathbb{A}}{\partial \mathbb{X}} = \begin{cases} \mathbb{A}^\top & \text{for general } \mathbb{X} \\ \mathbb{A} + \mathbb{A}^\top - \text{diag}(\mathbb{A}) & \text{for } \mathbb{X} \text{ symmetric} \end{cases}$$

# Statistical properties $\widehat{\mathbb{B}}_N$ and $\widehat{\Sigma}_N$

- the estimates in  $\widehat{\mathbb{B}}_N$  are **unbiased** estimates for  $\mathbb{B}$
- for  $\widehat{\mathbf{U}} = \mathbf{Y} - \mathbf{X}\widehat{\mathbb{B}}_N$  it holds that  $E\widehat{\mathbf{U}} = \mathbf{0}$
- $\widehat{\mathbb{B}}_N$  and  $\widehat{\mathbf{U}}$  are **multivariate normal**
- $\widehat{\mathbb{B}}_N$  and  $\widehat{\mathbf{U}}$  are **statistically independent**
- **covariance** between  $\widehat{\beta}_{ij}$  and  $\widehat{\beta}_{kl}$  is equal to  $\sigma_{jl} \cdot (\mathbf{X}^\top \mathbf{X})_{(ik)}^{-1}$
- $N\widehat{\Sigma}_N \sim W_n(\Sigma, N - p)$